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#include <iostream>
#include <cstdlib>
#include <stdlib.h>
#include <stdio.h>
#include <cstring>
#include <string>
#include <sstream>
#include <fstream>
#include <algorithm>
#include <math.h>
using namespace std;
//                                     Banker's Algorithm of allocating resources
//

const size_t MAX_TASKS=20;
const size_t MAX_RES=30;
enum command_t {Initiate, Request, Release, Compute, Terminate}; //Possible commands
enum task_state {blocked, running, aborted};
struct res { //Resources kept here
    int r_type;
    int units;
    } resources[MAX_RES];
struct comm { //List of allocation commands
    int task_id;
    command_t cmd;
    int r_type;
    int units;
    } commlist[MAX_RES];

struct tsk { //Array to keep basic info about the tasks
    int task_id;
    task_state state;
    struct tskact *taskp;
    } task_array[MAX_TASKS];

struct tskact { //This structure keeps the activities for each task
    command_t cmd;
    int r_type;
    int units;
    struct tskact *next; //It is kept as FIFO linked list
    } task_activity;

struct stats { //Here we keep statistics about tasks, to generate the output
    char * status;
    int time;
    int wait;
    } t_stats[MAX_TASKS];

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int curr[MAX_TASKS][MAX_RES]; //Current allocation of resources
int maxalc[MAX_TASKS][MAX_RES]; //Maximum claims
int save_curr[MAX_TASKS][MAX_RES]; //To facilitate safety check
int release_curr[MAX_TASKS][MAX_RES]; //To facilitate provisional release

int avail[MAX_RES];
int save_avail[MAX_RES];
int provisional_avail[MAX_RES]; // "in cycle" release of resources

//FUNCTIONS PROTOTYPES

void print_c(struct comm [],int);
void init_storage(int,int);
bool safe(int, int);
void print_matrix(int[][MAX_RES],int, int);
void backup_state(int, int);
void restore_state(int, int);
void print_array(struct tsk [], int);
void print_stats(struct stats [], int);
void update_provisional(int [], int [],int);
bool exceed(int, int);
void init_stats(struct stats [], int);
void grant(int, int, int);
void sort_task(struct tsk [],int);
void init_provisional(int [], int);
void init_matrix(int[][MAX_RES], int, int);
void update_curr(int[][MAX_RES], int, int);

//----- MAIN

int main (int argc, char * const argv[]) {

char *in_file;
in_file=argv[1];
fstream in(in_file, ios::in);
if (!in){ cout << "\n Input cannot be opened" <<
"\n Please check file: " << in_file << "\n";
exit(1);
}

char tk[10];
int t1, r1; //t1 - number of tasks, r1 - number of resources
int c_i=1; int task, resource, u, cyc;

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//Reading the resources pool

in >> tk;
t1=atoi(tk); cout << "\n T=" << t1 << "\n";
in >> tk;
r1=atoi(tk); //# resource types
cout << "\n R=" << r1 << "\n";
for(int i=1; i<=r1;++i){
    in >> tk; u=atoi(tk);
    resources[i].r_type=i;
    resources[i].units=u;
    //cout << "\n Resource type " << resources[i].r_type;
    //cout << "\n units=" << resources[i].units;
}

//Reading the allocation instructions

char comm_in[10];
in >> tk; strcpy(comm_in,tk);
while(in) {
    //The 3rd character in comm_in, identifies the command
    char comm_id = *(comm_in+2); //cout << "\n comm_id=" << comm_id;
    //bexit(1);
    switch(comm_id){
        case 'i': //Initiate
            commlist[c_i].cmd=Initiate;
            in >> task; in >> resource; in >> u;
            commlist[c_i].task_id=task;
            commlist[c_i].r_type=resource;
            commlist[c_i].units=u;
            break;
        case 'q': //Request
            commlist[c_i].cmd=Request;
            in >> task; in >> resource; in >> u;
            commlist[c_i].task_id=task;
            commlist[c_i].r_type=resource;
            commlist[c_i].units=u;
            break;
        case 'l': //Release
            commlist[c_i].cmd=Release;
            in >> task; in >> resource; in >> u;
            commlist[c_i].task_id=task;
            commlist[c_i].r_type=resource;
            commlist[c_i].units=u;
            break;
        case 'm': //Compute

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        commlist[c_i].cmd=Compute;
        in >> task; in >> cyc;
        commlist[c_i].task_id=task;
        commlist[c_i].r_type=0; //CPU is the resource
        commlist[c_i].units=cyc;
        break;
    case 'r': //Terminate
        commlist[c_i].cmd=Terminate;
        in >> task;
        commlist[c_i].task_id=task;
        commlist[c_i].r_type=0;
        commlist[c_i].units=-1;
        break;
    default : cout << "\n char is: " << comm_id;
              cout << "\ninvalid command encountered. Terminates.\n";
} //switch
++c_i;
in >> comm_in;
} //While input
//End of input processing

//Build Available resource array (initial availability of course)
for (int i=1;i<=r1;++i){
    avail[i]=resources[i].units;
}

//Initialize maxalc, curr allocation matrices
init_storage(t1,r1);

/*Build matrix of maximum allocation requested by all tasks for all resources
for (int i=1;i<c_i;++i){
    if (commlist[i].cmd==Initiate){
        maxalc[commlist[i].task_id][commlist[i].r_type]+=commlist[i].units;
    }
}
*/
cout << "\n Command list:\n";
print_c(commlist,c_i);
//cout << "\nCurr allocation:\n";
//print_matrix(curr,t1,r1);
//cout << "\nMAX allocation:\n";
//print_matrix(maxalc,t1,r1);

/*****
* Built the construct of array of pointers, each of which belongs to one task *
* and points to a linked list that contains all the activities we need to *
* perform on those tasks. *
*****/

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/*****/
int ind; //struct tskact *p;
for (int i=1; i<t1; ++i){ //Initialize array of pointers to activities
    task_array[i].taskp = NULL;
    task_array[i].task_id=0;
}

//cout << "\n BUILDING THE FIFO\n";
for (int l=1; l<c_i; ++l){
    ind=commlist[l].task_id;

    if (task_array[ind].task_id==0){ //First activity for the task, create entry
        task_array[ind].task_id=ind; //Initially the array's index=task ids
        task_array[ind].state=running; //zero excluded
    }
    if ( task_array[ind].taskp==NULL){
        task_array[ind].taskp=(struct tskact *) malloc(sizeof(struct tskact));
        task_array[ind].taskp->cmd =commlist[l].cmd;
        task_array[ind].taskp->r_type =commlist[l].r_type;
        task_array[ind].taskp->units =commlist[l].units;
        task_array[ind].taskp->next =NULL;
    }

    else{ // The array entry already has an activity(ies) add more
        struct tskact *q; struct tskact *t;
        q=task_array[ind].taskp;
        while (q->next !=NULL) q=q->next;

        t=(struct tskact *) malloc(sizeof(struct tskact));
        t->cmd =commlist[l].cmd;
        t->r_type =commlist[l].r_type;
        t->units =commlist[l].units;
        t->next =NULL;
        q->next = t;
    }
}

/* DEBUG
cout << "\n TASK ARRAY";
struct tskact *p; char *desc;
for (int z=1; z<=t1; ++z){
    p=task_array[z].taskp;
    while (p!=NULL){
        switch(p->cmd){
            case Initiate: desc="initiate"; break;
            case Request: desc="request"; break;

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        case Release:   desc="release";   break;
        case Compute:  desc="compute";   break;
        case Terminate: desc="terminate"; break;
        default:       cout << "invalid command";
    }

    cout << "\n Element:" << z << " Command=" << desc << " R TYPE=" << p->r_type << " UNITS=" << p->units;
    p=p->next;
}
}
END DEBUG */

//PROGRAM EXECUTION
int tasknum; struct tskact *activity;
bool all_tasks_terminated=false; //We assume that some tasks are ready to run
int cycle=0; bool ac_complete; //Check if activity was complete

//DEBUG
cout << "\nResource available before run:\n";
for (int i=1;i<=r1;++i){
    cout << "\n resource: " << i << " Units=" << avail[i] << "\n";
}

init_stats(t_stats,t1); int sum_t; int i1;
init_provisional(provisional_avail,r1); //Empty provisional release array
init_matrix(release_curr,t1,r1); //and image of current allocation
while (!all_tasks_terminated){ //Not really necessary here, but keeping good form
    cout<< "\n\n ARRAY_TASK before cycle:" << cycle;
    print_array(task_array, t1);
    cout << "\nCurr allocation:\n";
    print_matrix(curr,t1,r1);

    //tc - is Task Counter
    //tc may not correspond to the task number because
    //we sort task_array, so "blocked" are treated first

    sum_t=0;
    for (int tc=1;tc<=t1;++tc){
        if (task_array[tc].task_id==0) break; //Meaning task terminated, go to next task
        tasknum=task_array[tc].task_id;
        if (task_array[tc].taskp==NULL){
            task_array[tc].task_id=0;
        }
        break;
    }
    //Debug
    cout << "\n\n TASK ID EXAMINED: " << task_array[tc].task_id << "\n\n";
}

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activity=task_array[tc].taskp; ac_complete=true;
//DEBUG
char *ac_desc;
switch(activity->cmd){
    case Initiate: ac_desc="initiate"; break;
    case Request: ac_desc="request"; break;
    case Release: ac_desc="release"; break;
    case Compute: ac_desc="compute"; break;
    case Terminate: ac_desc="terminate"; break;
    default: cout << "invalid command";
}

cout<< "\n\n Checking, task: " << tasknum << " activity:" << ac_desc << " Resource T:" <<
    activity->r_type << " units:" << activity->units;
cout << "\nResource available, before SWITCH:\n";
for (int i=1;i<=r1;++i){
    cout << "\n resource: " << i << " Units=" << avail[i] << "\n";
}

switch (activity->cmd){
    case Initiate:
        /*****
        * During the course of initiation(which is done before requests), the avail array*
        * still holds the initial availability, which is known in advance from the input *
        * and therefore allows us to check that initiate does not exceed availability *
        *****/
        if (exceed(activity->r_type,activity->units)){ //ERROR DETECTION
            cout << "\n Banker aborts task: " << tasknum << " before execution";
            cout << "\n Initial claim of task: " << tasknum << " is: " <<
                activity->units << " units of resource type: " << activity->r_type <<
                " which exceeds maximum of: " << avail[activity->r_type] << " available";
            task_array[tc].task_id=0;
            task_array[tc].state=aborted;
            t_stats[tasknum].status="aborted";
            //ABORT
        }
        else {
            maxalc[tasknum][activity->r_type]+=activity->units;
        }
        cout << "\n MAX allocation after this initiate:\n";
        print_matrix(maxalc,t1,r1);
        cout << "\nCurr allocation, after initiate:\n";
        print_matrix(curr,t1,r1);
        cout << "\nResource available, after initiate:\n";
        for (int i=1;i<=r1;++i){

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        cout << "\n resource: " << i << " Units=" << avail[i] << "\n";
    }

    break;
case Compute:
    --activity->units;
    if (activity->units >0) ac_complete=false; //Incomplete activity
    break;
case Release:
    provisional_avail[activity->r_type]+=activity->units;
    release_curr[tasknum][activity->r_type]+=activity->units;
    /*debug*/ cout << "\n RELEASE Curr allocation:\n";
    print_matrix(release_curr,tl,r1);

    break;
case Terminate:
    task_array[tc].task_id=0;
    t_stats[tasknum].status="ended";
    for(il=1;il<=r1;++il) maxalc[tasknum][il]=0; //This task no onger claims resources
    break;
case Request: // if Request for resource +in-use exceed maximum pledged - abort task
    if (maxalc[tasknum][activity->r_type]<
        activity->units +curr[tasknum][activity->r_type]){
        task_array[tc].task_id=0;
        task_array[tc].state=aborted;
        t_stats[tasknum].status="aborted";
        ac_complete=false;
        cout<< "\nTask number: " << tasknum << " asked for:" << activity->units <<
            " of resource type:" <<activity->r_type << " and has already:" <<
            curr[tasknum][activity->r_type] << " units of it. It originally asked for:"
            << maxalc[tasknum][activity->r_type] << " maximum";
    }
    else {
        backup_state(tl,r1); //Save state in case it would be unsafe
        //Firstly, grant the request temporarily
        grant(tasknum,activity->r_type, activity->units);

        //DEBUG
        cout << "\n CALLING SAFE with:" << " t1=" << t1 << " r1=" << r1;
        cout << "\nResource available after temp GRANT and before SAFE:\n";
        for (int i=1;i<=r1;++i){
            cout << "\n resource: " << i << " Units=" << avail[i] << "\n";
        }
        cout << "\nCurr allocation:\n";
    }
    print_matrix(curr,tl,r1);
    cout << "\nMAX allocation:\n";
    print_matrix(maxalc,tl,r1);

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//END DEBUG

        if (safe(tl, r1)){ //contingent safety
            restore_state(tl,r1);
            grant(tasknum,activity->r_type, activity->units); //Now grant it for real
            task_array[tc].state=running;
            cout << "\nREQUEST GRANTED\n";

        }
        else { //Request denied, task blocked (unsafe)
            cout << "\nREQUEST NOT GRANTED\n";
            restore_state(tl,r1);
            ac_complete=false; //Incomplete activity
            t_stats[tasknum].wait++;
            task_array[tc].state=blocked;
        }
    }
    break;
default: cout << "\n Other UNKNOWN command";
    break;
}
if (ac_complete){ //Incomplete activity is compute that hasn't ended yet, or request denied
    task_array[tc].taskp=task_array[tc].taskp->next; //Drop the activity after its complete
                                                    //will become NULL if activity is Terminate
}
if ( task_array[tc].task_id > 0) //one more cycle added to task's time
    t_stats[tasknum].time++;

//free(activity);
}
update_provisional(avail,provisional_avail,r1); //Update resource vetor and current allocation
update_curr(release_curr, t1, r1); //matrix with resources released in the last cycle
init_provisional(provisional_avail,r1); //Initialize the temp storage for next cycle
init_matrix(release_curr,t1,r1); //both current allocation and avail resource vetor
++cycle;
sort_task(task_array,t1); //Sorting task array, so the blocked tasks are ahead of others
for(int l1=1;l1<=t1;++l1){
    sum_t+=task_array[l1].task_id;
}
if (sum_t==0) all_tasks_terminated=true; sum_t=0;

// DEBUG
if (cycle >22){
    all_tasks_terminated=true;
}
//

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}

//DEBUG
cout << "\nResource available AFTER run:\n";
for (int i=1;i<=r1;++i){
    cout << "\n resource: " << i << " Units=" << avail[i];
}

cout << "\nMAX allocation:\n";
print_matrix(maxalc,t1,r1);
//END DEBUG
print_stats(t_stats,t1);

return 0;
}

//Functions
//-----
void print_c(struct comm q[], int len){
    char *comm_desc;
    for (int i=1; i<len;++i){
        switch(q[i].cmd){
            case Initiate: comm_desc="initiate"; break;
            case Request:  comm_desc="request";  break;
            case Release:  comm_desc="release";  break;
            case Compute:  comm_desc="compute";  break;
            case Terminate: comm_desc="terminate"; break;
            default: cout << "invalid command";
        }
        cout << "\n" << comm_desc << " " << q[i].task_id << " " << q[i].r_type <<
            " " << q[i].units;
        cout << "\n";
    }
}

//-----
bool safe(int running_tasks, int resources){

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bool safe; int unfinished=running_tasks; int i, j;
while (unfinished > 0){
    i=1; safe=false;
    while (i<= running_tasks && !safe){ //Assume it's not safe and look for a task that can complete
        if (curr[i][1] != -1){ // I mark tasks that can complete with -1
            safe=true;
            j=1;
            while (j<= resources) { // Check if we can satisfy all resources
                if ((maxalc[i][j]-curr[i][j]) > avail[j]){
                    safe=false; //It is enough that we faile once, to try next task
                    break;
                }
                ++j;
            }
            ++i;
        }
    }
    if (safe){
        --unfinished; //One less task to check
        --i;
        for (j=1;j<=resources;++j){ //Release the resources back to the pool
            avail[j]+=curr[i][j];
        }
        curr[i][1]=-1; //Mark the task as complete for now
    }
    else{
        return false; //It was unsafe (no task can complete)
    }
}
return true; //If we made it here, it means all tasks can complete (no unfinished) ==> SAFE
}
//-----
void init_storage(int tasks, int resources){
    for (int i=1;i<=tasks;++i){
        for (int j=1;j<=resources;++j){
            maxalc[i][j]=0; curr[i][j]=0;
        }
    }
}
//-----
void init_matrix(int m[][MAX_RES], int t, int r){
    for (int i=1;i<=t;++i){
        for (int j=1;j<=r;++j){
            m[i][j]=0;
        }
    }
}

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}

//-----
void init_stats(struct stats s[], int t){
    for (int i=1;i<=t;++i){
        s[i].status="";
        s[i].time=0;
        s[i].wait=0;
    }
}

//-----
void print_matrix(int matrix[][MAX_RES],int t, int r){
    for (int i=1;i<=t;++i){
        cout << "\Task: " << i << " ";
        for (int j=1;j<=r;++j){
            cout << "Resource type=" << j << " Units allocated=" << matrix[i][j] << " ";
        }
        cout << "\n";
    }
}

//-----
void backup_state(int t, int r){
    int k1, k2;
    for (k1=1;k1<=t;++k1){
        for (k2=1;k2<=r;++k2){
            save_curr[k1][k2]=curr[k1][k2];
        }
    }
    for (k2=1;k2<=r;++k2){
        save_avail[k2]=avail[k2];
    }
}

//-----
void restore_state(int t, int r){
    int k1, k2;
    for (k1=1;k1<=t;++k1){
        for (k2=1;k2<=r;++k2){
            curr[k1][k2]=save_curr[k1][k2];
        }
    }
    for (k2=1;k2<=r;++k2){
        avail[k2]=save_avail[k2];
    }
}

//-----
void update_provisional(int r1[], int r2[], int r){ //adding resources from r2 array to r1 array

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    int k;
    for (k=1;k<=r;++k){
        r1[k]+=r2[k];
    }
}
//-----
void update_curr(int c[][MAX_RES], int t, int r){ //After "release", the current allocation is reduced
    int k1, k2;
    for (k1=1;k1<=t;++k1){
        for (k2=1;k2<=r;++k2){
            curr[k1][k2]-=c[k1][k2];
        }
    }
}
//-----

void print_array(struct tsk a[], int elements){
    char *desc; struct tskact *p;
    for (int i=1; i<=elements;++i){
        if (a[i].state==blocked) desc="blocked";
        if (a[i].state==aborted) desc="aborted";
        if (a[i].state==running) desc="running";

        cout << "\n Task id=" << a[i].task_id << " state= " << desc;
        p=a[i].taskp;

        if (p!=NULL){
            switch(p->cmd){
                case Initiate: desc="initiate"; break;
                case Request: desc="request"; break;
                case Release: desc="release"; break;
                case Compute: desc="compute"; break;
                case Terminate: desc="terminate"; break;
                default: cout << "invalid command";
            }

            cout << "\n Activity:" << desc;
            cout << "\n Resource:" << p->r_type;
            cout << "\n Units : " << p->units;
        }
        else {
            cout << "\n NO MORE ACTIVITIES FOR THIS TASK\n";
        }
        /*
        while (p!=NULL){
            cout << " Activity:" << p->cmd;

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        p=p->next;
    }
    */
}
//-----
void print_stats(struct stats s[], int t){
    double percent_w; double wait;
    double time; double tot_time=0; double tot_wait=0; double percent_av;
    for (int i=1;i<=t;++i){
        wait= (double) s[i].wait;
        time = (double) s[i].time;
        if (time > 0) percent_w = (wait/time)*100;
        else percent_w = 0;
        cout << "\n Task number:" << i;
        if ( !strcmp(s[i].status,"aborted")){ //Task was aborted
            cout << "      aborted";
        }
        else{
            cout << "      " << s[i].time << "      " << s[i].wait <<
            "      " << percent_w << "%";
            tot_time+=s[i].time; tot_wait+=s[i].wait;
        }
    }
    if (tot_time > 0) percent_av = (tot_wait/tot_time)*100;
    else percent_av = 0;
    cout << "\n Total:      " << tot_time << "      " << tot_wait << "      " << percent_av<<"%\n";
}
//-----
bool exceed(int r, int u){
    if (avail[r]< u)
        return true;
    else
        return false;
}
//-----
void grant(int tn, int r, int u){
    avail[r]-=u;
    curr[tn][r]+=u;
}
//-----
void sort_task(struct tsk v[], int t){
    int temp1; struct tskact *temp2; task_state temp3;
    bool sw;
    do{
        sw = false;

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        for(int i = 1; i <= t-1; i++){
            if(v[i].state > v[i + 1].state){
                temp1 = v[i].task_id;    v[i].task_id = v[i+1].task_id;    v[i+1].task_id = temp1;
                temp2 = v[i].taskp;      v[i].taskp=v[i+1].taskp;      v[i+1].taskp=temp2;
                temp3 = v[i].state;      v[i].state=v[i+1].state;      v[i+1].state=temp3;
                sw=true;
            }
        }
    } while(sw);
}
//-----
void init_provisional(int v[], int r){
    for (int i=1;i<=r;++i){
        v[i]=0;
    }
}
//-----

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